

Constraining surface-effect corrections for solar-like oscillations using 3D hydrodynamical simulations

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Surface effects on solar-like oscillations

- Good mode identification of solar-like oscillations is expected to be powerful for seismic inference.
- “Surface effects” prevent us from making the best of the high precision.
 - Poor modelling (of turbulent pressure) in near-surface regions
 - Systematic differences between observed and model frequencies for the Sun

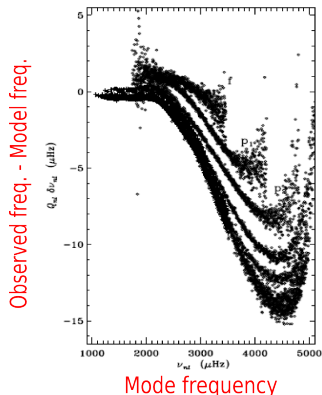


Figure : Solar case (Rosenthal+ 1999)

Empirical correction of model frequencies

- **Kjeldsen+ (2008) proposed an empirical power-law correction,**

$$\nu_{\text{obs}} - r\nu_{\text{ref}} = a \left(\frac{\nu_{\text{obs}}}{\nu_0} \right)^b,$$

with $b = 4.9$ calibrated to the Sun.

- **Many studies adopted this functional and this value of b to correct model frequencies of other stars.**

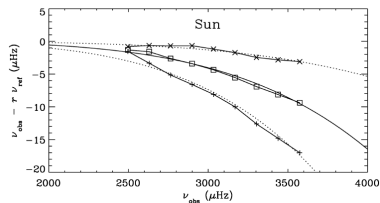


FIG. 1.—Difference between observed and calculated frequencies for radial modes in the Sun. The squares are for model S, with the solid curve showing a fit to eq. (4) with $r = 1$, which gives $b = 4.90$ (see § 3). Also shown are the results of applying the same corrections to model S⁻ (crosses) and model S⁺ (pluses). The dotted curves show the corrections calculated from eq. (4).

Figure : Kjeldesen+(2008)

Considerations of surface effects for the Sun

- **Effects of modelling of equilibrium structure**
(e.g. Christensen-Dalsgaard+1997, Rosenthal+1999, Houdek+2010)
- **Effects of modelling of eigenmodes**
 - ▶ **Wave propagation through convective flows**
(e.g. Bhattacharya+2015)
 - ▶ **Non-adiabatic effects with TDC**
(e.g. Houdek+2010, Grigahcene+2013)

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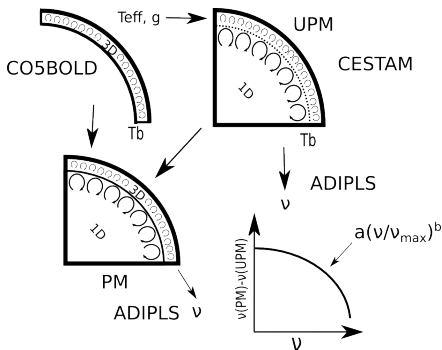
⇒ Aim of this work

Constrain surface-effect correction using set of 3D simulations **across $T_{\text{eff}} - g$ plane**

Method

Fit the correction functional to the frequency difference between realistic models (patched models, PMs) and standard models (unpatched models, UPMs).

- CO⁵BOLD (Freytag+2012) with CIFIST grid (Ludwig+2009) for 3D hydrodynamic simulations
- CESTAM (Marques+2013) for 1D standard models



Validity of PM

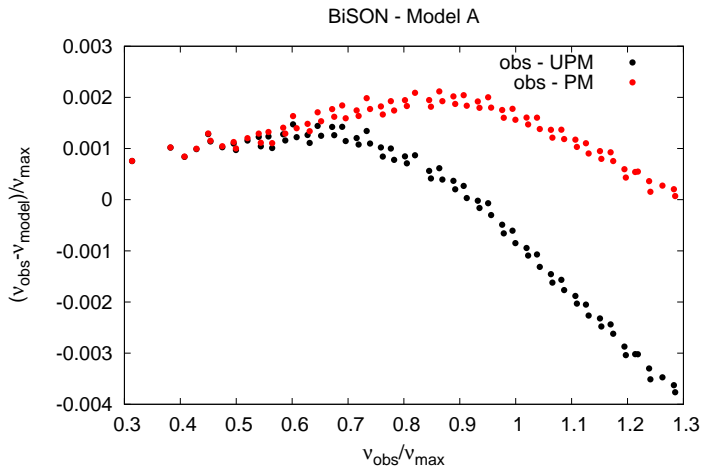


Figure : Frequency differences between BiSON frequencies (Table 3 of Broomhall et al. (2009)) and PM or UPM for model A ($T_{\text{eff}} = 5775$ K, $\log g = 4.44$), which is close to the Sun.

Fit to frequency differences between PM and UPM

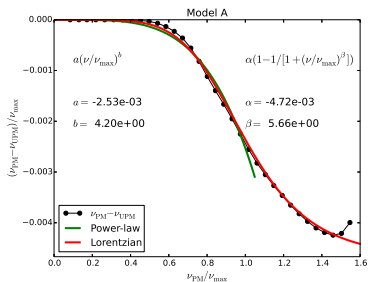


Figure : Model A ($T_{\text{eff}} = 5775$ K, $\log g = 4.44$, close to the Sun)

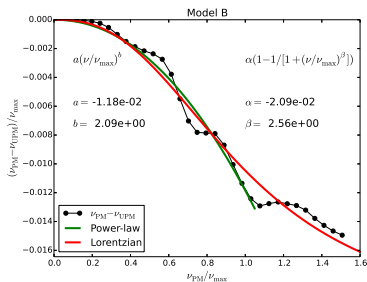


Figure : Model B ($T_{\text{eff}} = 6725$ K, $\log g = 4.25$)

- Power law (Kjeldsen+ 2008)

$$\frac{\delta\nu}{\nu_{\max}} = a \left(\frac{\nu}{\nu_{\max}} \right)^b$$

- Modified Lorentzian function

$$\frac{\delta\nu}{\nu_{\max}} = \alpha \left[1 - \frac{1}{1 + (\nu/\nu_{\max})^\beta} \right] \quad \left[\rightarrow \alpha \left(\frac{\nu}{\nu_{\max}} \right)^\beta \quad (\nu \ll \nu_{\max}) \right]$$

a and α in $T_{\text{eff}} - g$ plane

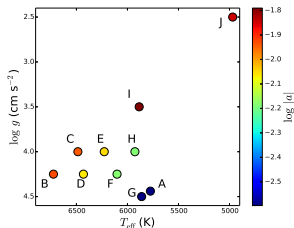


Figure : $a(\nu/\nu_{\text{max}})^b$

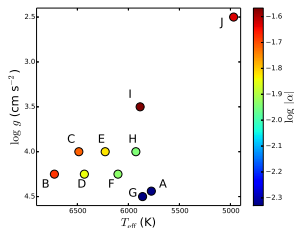


Figure : $\alpha(1 - 1/[1 + (\nu/\nu_{\text{max}})^\beta])$

$$\log(-a) = 8.13 \log T_{\text{eff}} - 0.670 \log g - 30.2$$

$$\log(-\alpha) = 7.69 \log T_{\text{eff}} - 0.629 \log g - 28.5$$

b and β in $T_{\text{eff}} - g$ plane

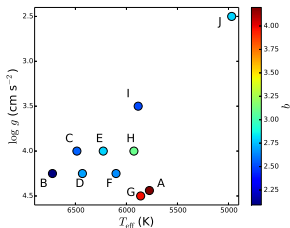


Figure : $a(\nu/\nu_{\text{max}})^b$

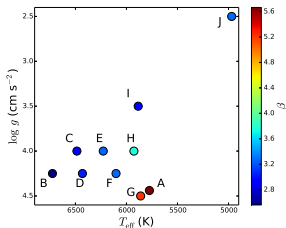


Figure : $\alpha(1 - 1/[1 + (\nu/\nu_{\text{max}})^\beta])$

$$\log b = -3.16 \log T_{\text{eff}} + 0.184 \log g + 11.7$$

$$\log \beta = -3.37 \log T_{\text{eff}} + 0.218 \log g + 12.4$$

- Change by a factor of $\simeq 2$

→ the solar calibrated index should not be used for other stars.

Lorentzian has smaller deviation than power law not depending on fitting ranges.

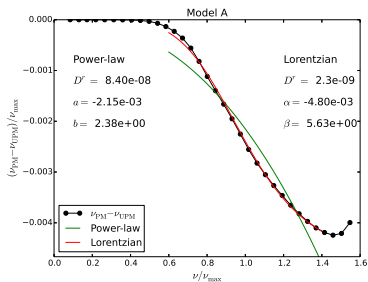


Figure : Fit in range $0.6 < \nu/\nu_{\max} < 1.4$

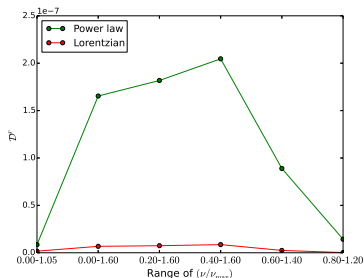


Figure : Deviation of fitting functions

Reduced deviation from the fitting functions $\delta\nu_i$:

$$\mathcal{D}^r = \frac{1}{N} \sum_i^N \left[\frac{\nu_{\text{PM},i} - \nu_{\text{UPM},i} - \delta\nu_i}{\nu_{\max}} \right]^2 \quad (i: \text{label of modes})$$

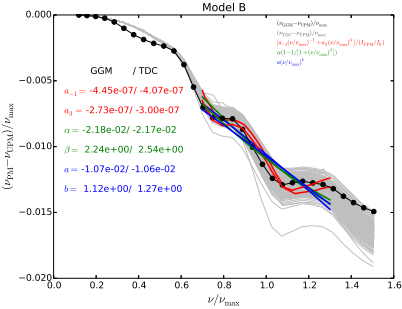
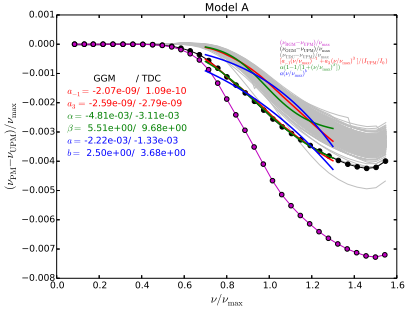
Conclusion

- The power indices of the frequency corrections certainly depend on T_{eff} and g .
- The Lorentzian is nicely fitted to the frequency difference between PM and UPM and is less sensitive to the frequency range than the power law.

Ongoing work

- Include perturbation of turbulent pressure and non-adiabatic process with TDC formalism using MAD code.

[Preliminary] Adiabatic TDC treatment (turbulent pressure perturbation included)



Dependence of a , α , b and β on fitting range

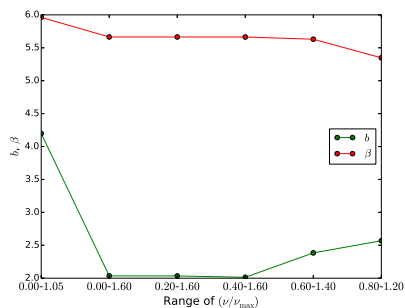
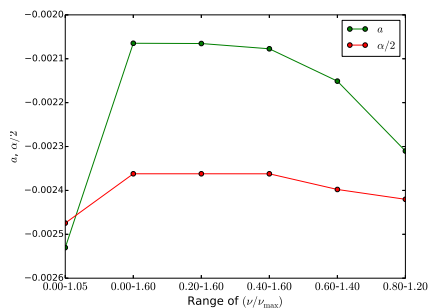
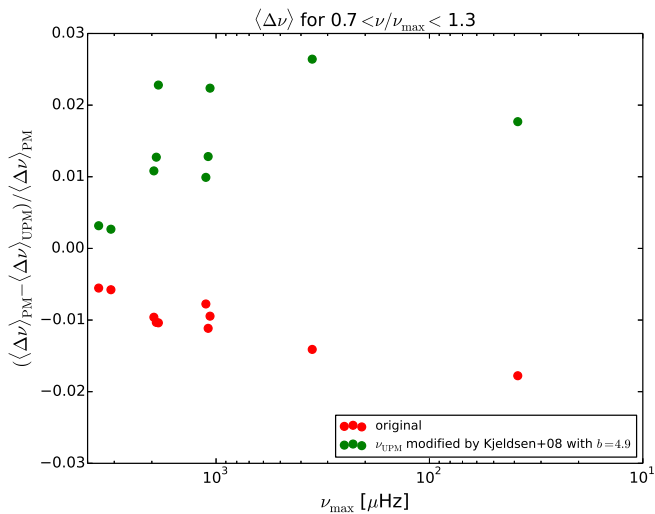
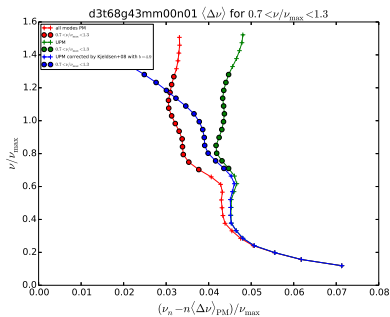
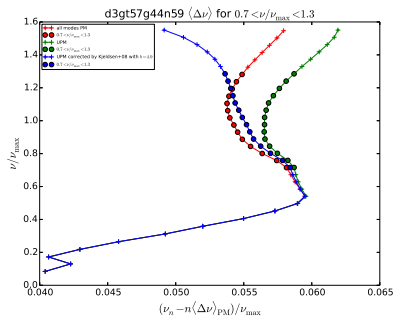


Figure : Model A

Effect of surface-effect correction on difference in large separation between PM and UPM



Effects of surface-effect correction in Echell diagrams



[Preliminary] Ball & Gizon (2014) fit

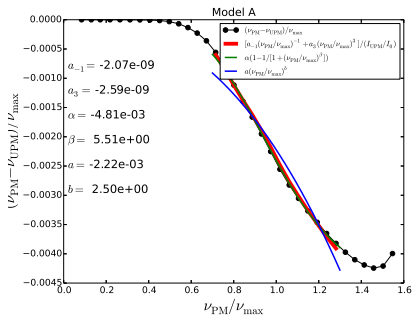


Figure : Model A (the Sun, $T_{\text{eff}} = 5775\text{K}$, $\log g = 4.44$)

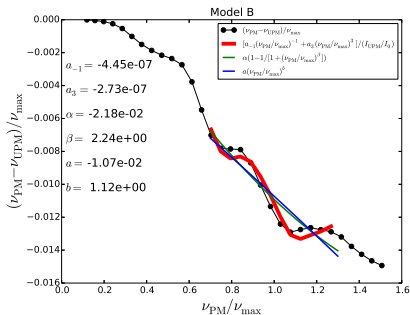
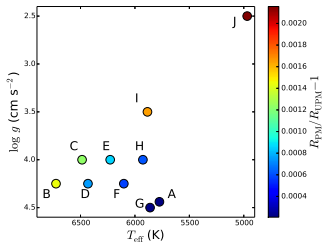
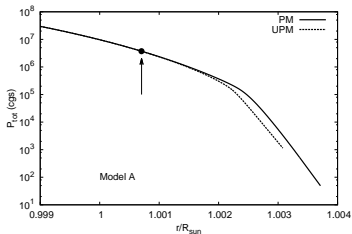


Figure : Model B ($T_{\text{eff}} = 6725\text{K}$, $\log g = 4.25$)

Elevation of outer layer due to turbulent pressure



Larger elevation with increasing T_{eff} or decreasing g , since

• $T_{\text{eff}} \uparrow \Rightarrow \text{superadiabaticity} \uparrow \Rightarrow v_{\text{conv}} \uparrow$

• $g \downarrow \Rightarrow \rho \downarrow \Rightarrow v_{\text{conv}} \uparrow$

$\Rightarrow P_{\text{turb}}/P_{\text{tot}} \uparrow$